

Charge

## **Power Electronics**

≤ 340 V

# Instrumented Load Bench with active load and Simulation of Digital Industrial Systems

#### Main features:

The load bench **BICSIN**, **EL320** belongs to the Low Voltage (LV) and Safety Extra Low Voltage (SELV) 300-W ranges, it is designed for:

- ELECTROTECHNICS, study of rotating machines characteristics (relation speed/voltage, current/torque, power efficiency, cosineq...),
- POWER ELECTRONICS, compatible with the range EP(S)1x0 EP(S)2x0, SELV or LV power converters (rectifiers, AC controllers, inverters...)
- > **AUTOMATIC CONTROL**, creation of a programmable mechanical load:
  - Passive load (braking load, linear or not linear) (Ventilator, drill, travel of a load with friction, vehicle in circulation; acceleration, slowing down with energy recovery .....)
  - Driving load, linear or not linear (overhead crane, fast elevator, steering wheel implying lively phases and energy recovering phase,
  - The load generator is instrumented, which enables to read in real-time the mechanical variables from the experimented machine (speed, torque, power)
  - It works, in accordance with the standard LV « Low Voltage,  $30/340 V_{DC}$  and  $240 V_{AC}$  »....
- AUTOMATIC SPEED / POSTION CONTROL Implementation of a control cabinet including various organs (industrial variator associated with its brushless motor, PLC, HMI.) to pilot an emulated automatism (enslaved digital axis, ventilator, barrier of parking lot). This solution has the immense advantage to allow a work of the student in complete safety

### **AREAS OF APPLICATION:**

Technical/Vocational training sectors, Prep schools, Universities, Engineering schools

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EL(S)32

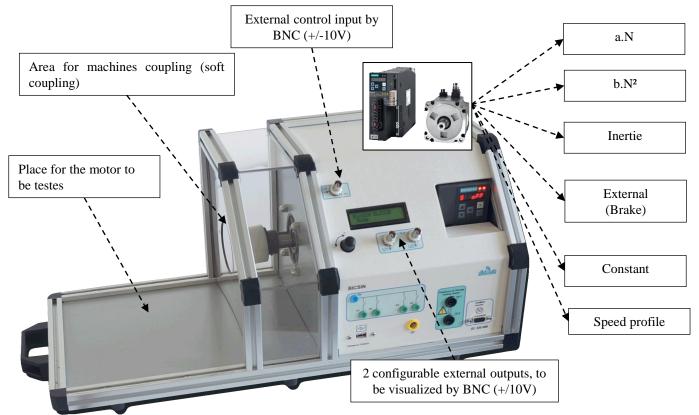
Packing:Net : 20 kg, Dimensions (Lx l x h) 80x30x30cmGross : 25 kg, Dimensions (Lx l x h) 100x40x38cm.

## **BICSIN-EL(S)320 – Description:**

BICSIN is a system which can be put on a table ; : it includes

- > One part for the load generation, made of a brushless motor with its industrial variator,
- ➤ A embedded 1-phase power supply
- ➤ A PC interface board (via USB),

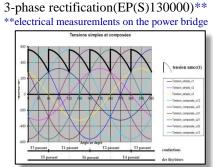
It is the ideal tool to study not only all the characteristics of 300W electric motors (DC, 3-ph AC, brushless motors.), to put a load on various types of power bridges (1 phase or 3 phase Graetz bridges, choppers, 1-phase / 3-phase inverters) and finally to emulate an industrial system like a digital axis, an elevator ...



#### EL(S)320100, Basic program, creation of loads and acquisition of mechanical variables

It is used to set the condition of the loads' creation, the data acquisiton for the response curves (speeds, torques, voltages ....) and the display of these responses

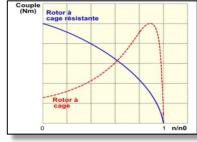
#### **Power electronics:**

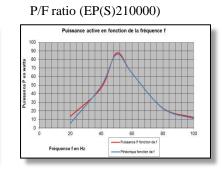


#### **Electrical engineering:**

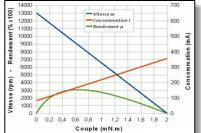
Torque Speed relation

3-phase asynchronous motor (EL(S)30300D)C motor (EL(S)302000)

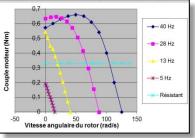




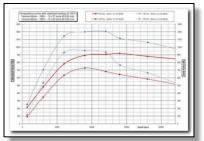
Torque Speed relation



Torque for asynchronous motor f N (EP(S)230000)



Torque Speed relation Brushless motor (EL(S)306000)



## Motors, for Low Voltage range (LV) :

You can put several motors on the bench. Usually, we suggest the following 6 motors in the LV range and 4 for the SELV range (at the bottom of the page). For other motors, please ask us.

EL 302000 : 300-W DC motor, with permanent excitation			EL 303000 : 300-W 3-phase Asynchronous motor				
	MOTOR CHARACTERISTICS	Value	Units		MOTOR CHARACTERISTICS	Value	Units
	Power voltage	170	Vdc		Power voltage	240	3xAC
	Speed (for nominal current)	2000	rpm		Speed (for nominal current)	1500	rpm
	Mechanical power	300	W		Mechanical power	300	W
	Nominal current	2,1	А		Nominal current	2	А
	Efficiency	77	%		Cos φ	0,74	

EL 301000 : 300-W DC motor, with separate excitation			EL 306000 : 300-W Brushless motor, 230Vac, 310Vdc				
	MOTOR CHARACTERISTICS	Value	Units		MOTOR CHARACTERISTICS	Value	Units
	Power voltage	170	Vdc		Power voltage	230	Vac
	Speed (for nominal current)	2000	rpm		Speed (for nominal current)	2000	rpm
	Mechanical power	300	W		Mechanical power	300	W
	Nominal current	2,1	А		DC voltage power supply	310	Vdc
	Excitation current	0,52	А		(trapezoïd)	210	· ac

EL 307000 : 1-ph, 3-ph asynchronous motor, 300 W			EL 305000 : 3-ph Synchronous motor / generator, 300 W				
	MOTOR CHARACTERISTICS	Value	Units		MOTOR CHARACTERISTICS	Value	Units
	Power supply	240	Vac		Power supply	230	Vac
	Speed (synchronism)	1500	rpm		Speed (for nominal current)	1500	rpm
	Electrical power	370	W		Mechanical power	300	W
	Nominal current	2,1	А		Nominal current	0,9	А
	Cos φ	0,74		P.	Efficiency	77	%

## Motors for Safety Extra Low Voltage range (SELV):

ELS 301000 : 300-W D	C motor, with separate exc	ELS 303000 : 300-W 3-phase Asynchronous motor			
	MOTOR CHARACTERISTICS	Value	Units		MOTOR CHARACTERISTICS
	Power supply 48 Vdc		Power supply		
	Speed (for nominal current)	2000	rpm		Speed (for nominal current)
	Electrical power	412	W		Operating power
	Nominal current	current 6,5 A			Nominal current
	Excitation current	1,4	А		Efficiency

ELS 302000 : 300-W DC motor, with permanent excitation			ELS 306000 : 300-W Brushless motor, 23Vdc				
	MOTOR CHARACTERISTICS	Value	Units		MOTOR CHARACTERISTICS	Value	Units
	Power supply	48	Vdc		Sine voltage power supply	23	Vac
	Speed (for nominal current)	2000	rpm		Speed (for nominal current)	2000	rpm
	Electrical power	321	W		Mechanical power	300	W
	Courant nominal	6,7	A	No. 1	DC voltage power supply	35	Vdc

Value

24/42

1500

180 11,5/6,6

0,68

Units

Vac

rpm W

А

%

## **BICSIN : Example of complete sets for Automatic control study**

#### Contol of a PLC/speed control with HIM

The BICSIN load bench allows the creation of scenarios representative of an industrial system. The example below is based on the BICSIN structure described at the beginning of this document, on which a SIMOTICS S1FL6 400W motor associated with its drive is implemented.

- Lot of experimetns can be carried out with this solution:
- ▶ Basic control of a brushless motor with an industrial motor drive,
- > Management of an automation sequence by PLC associated with a drive,
- Management of a complete automatic system under TIA Portal
- ➤ Control of the traction of an electric vehicle.



## Management of a speed regulation of asynchronous (or Brushless) power-driven electric vehicle

- > Characterization of an open-loop system (time constant, inertia, determination of the order)
- > Management of the starting up with control of acceleration, speed regulation by PI,
- Regulation of the speed of a vehicle by PI in various situations of traffic (On plain road, in rise, in descent,, empty vehicle, full loaded vehicle...)



### Standard configurations:

Ref	Ref 32_ B	Description				
BICSIN, Banc Instrumenté de Charge & émulation de Systèmes Industriels Numériques incluant :						
EL(S)	320000	Test motor bench with active load (the load is a brushless motor controlled by a				
		SINAMICS V90 drive), control electronic board with speed and torque measures				
		Set on a aluminium frame with carrying handles				
EL(S)	320100	Basic program, creation of loads and acquisition of mechanical variables (speed,				
		torque, power)				
		Motors :				
EL(S)	30 <u>2</u> 000	300-W DC motor, with permanent excitation				
EL(S)	30 <u>3</u> 000	300-W 3-phase asyncronous motor				
EL(S)	30 <u>6</u> 000	300-W Brushless motor,				
EL(S)	30 <u>X</u> 000	Ohter motors : please ask				
		Optional extra (still under development):				
EL(S)	320 200	System for real time simulation for industrial processes				

#### **Example of setting:**

EL<u>326</u>B, BICSIN 320, configured with : active load (brushless motor) and mechanical measurements and a brushless motor (C=6).

