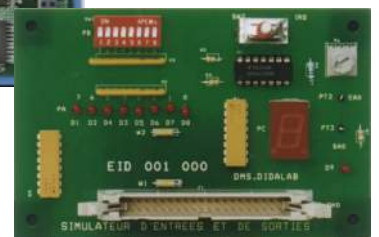


# EXPERIMENTS MANUAL

## On EID210 System + "Inputs / Outputs Simulator" Module



**Sample**

## SUMMARY

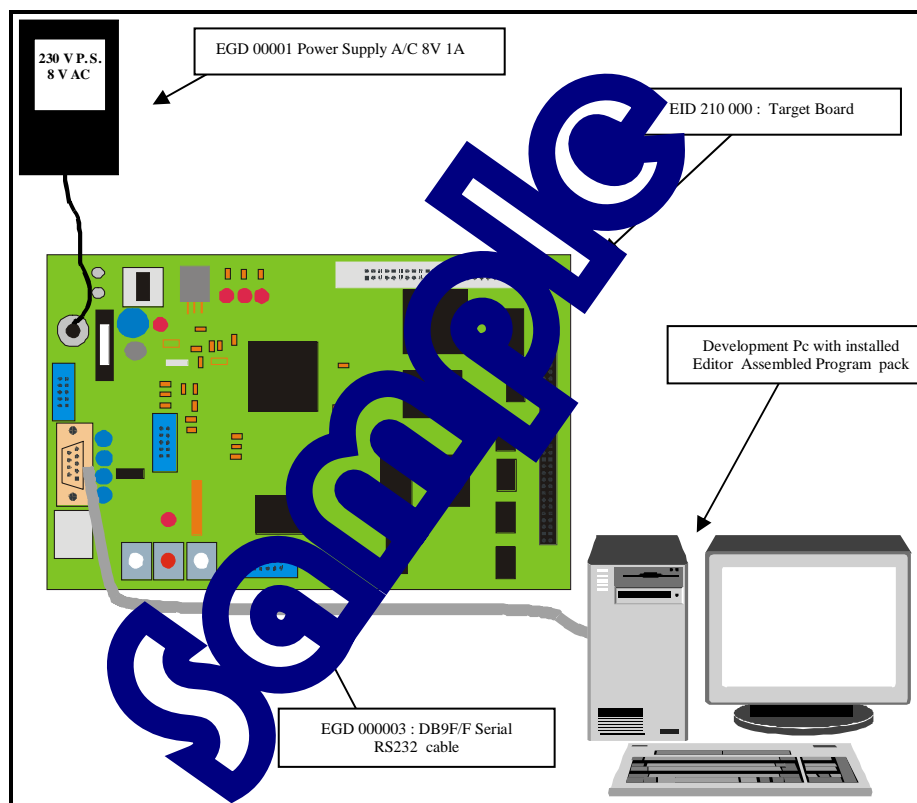
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Sample

**Sample**

## INSTALLATION OF THE EQUIPMENT

- > **Connect** the EID 210 000 board to the development PC with Assembler language (provided together with the equipment and beforehand installed in accordance with the technical manual), in using the USB cable or if unavailable, the RS232 serial cable.
- > **Plug** the Power Supply onto the EID 210 000 Board , (from 7 to12 V AC or DC),
- > **Connect** the EID 001 000 Inputs Outputs Simulator to the EID 210 000( CPU Board).
- > **Press** down the EID 210 000 Board On/Off pushbutton, the red light must go on.



**Sample**

# EXPERIMENT N° 1- SEQUENTIAL SHIFT DEVICE WITH LEDS ONTO PORT A

## 1.1 Topic

<b>Object :</b>	<p>Being capable of configuring one port into Output and activating these Outputs (This port is one element of the micro-controller « TPU »).</p> <p>Being capable of analysing imposed specifications and writing a program for complying with it.</p> <p>Being capable of carrying out a program time delay, then using the Micro-controller "TIMER" function.</p> <p>Being capable of carrying out a program in Assembler language</p>
<b>Specifications :</b>	<p>A light shift device is implemented in using the 8 Leds connected onto port A of EID210 Processor board.</p> <p>Which leads to the following sequence: D8 on, then wait for 0,5S, then D7 on, then wait for 1S, etc...</p> <p>After D8 turning on there is a loop, which means that we come back to D8.</p> <p><i>Variant 1</i> The delay is carried out by program waiting loop.</p> <p><i>Variant 2</i> The delay is carried out in using the micro-controller internal "TIMER".</p>

### Necessary Equipment :

PC Micro-Computer using Windows © 95 or latter,  
 68332 Micro-Controller 16/32 bits Mother Board, Ref. : EID 100 000  
 USB link cable or if unavailable, RS232 cable, Ref. : EGD 000 003  
 AC/AC 8V Power Supply, 1 A, Ref. : EGD000001,  
 Input / Output Simulator, Ref. : EID001000

Duration : 4 hours





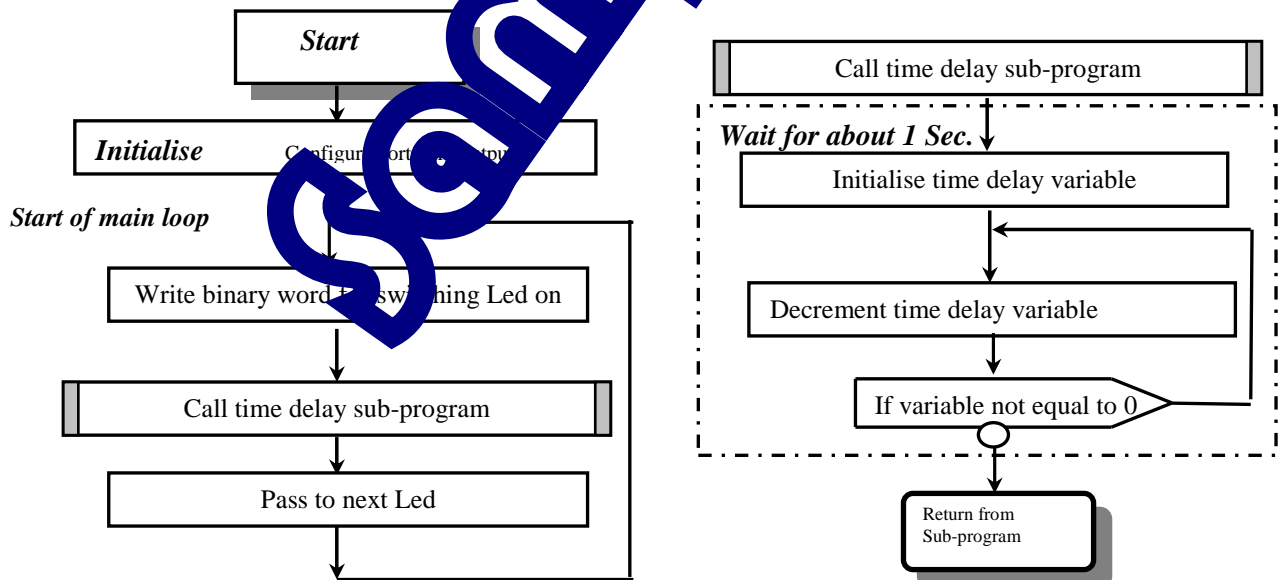
For carrying out the light shift device following the sequence requested by specifications, the following sequence must be written into register HSSR1:

N° Leds	D1	D2	D3	D4	D5	D6	D7	D8	
Logic states	1	1	1	1	1	1	1	0	
Value register HSSR1	0 1	0 1	0 1	0 1	0 1	0 1	0 1	1 0	-> \$5556
Logic states	1	1	1	1	1	1	0	1	
Value register HSSR1	0 1	0 1	0 1	0 1	0 1	0 1	1 0	0 1	-> \$5559
Logic states	1	1	1	1	1	0	1	1	
Value register HSSR1	0 1	0 1	0 1	0 1	0 1	1 0	0 1	0 1	-> \$5565
Logic states	1	1	1	0	1	1	1	1	
Value register HSSR1	0 1	0 1	0 1	1 0	0 1	0 1	0 1	0 1	-> \$5655
Logic states	1	1	0	1	1	1	1	1	
Value register HSSR1	0 1	0 1	1 0	0 1	0 1	0 1	0 1	0 1	-> \$5955
Logic states	1	0	1	1	1	1	1	1	
Value register HSSR1	0 1	1 0	0 1	0 1	0 1	0 1	0 1	0 1	-> \$6555
Logic states	0	1	1	1	1	1	1	1	
Value register HSSR1	1 0	0 1	0 1	0 1	0 1	0 1	0 1	0 1	-> \$9555

### Carrying out of programmable time delay:

A programmable time delay is carried out by initializing a variable at a determined value and decrementing this value till it becomes equal to zero. The decrementation loop operation duration, carried out "n" times ( n = initial value of the variable) represents the required lapse of time. On the program thereafter, the variable is included into the next program operation.

#### 1.2.2 Flowchart, solution with programmable time delay :



### 1.2.3 Program in A68xxx Assembler with time delay loop

```

*****
* EXPERIMENTS ON EID210 BOARD WITH INPUTS/OUTPUTS SIMULATOR *
* Carrying out of light shift device on Leds of port A *
*****
* Specifications : *
*****
* Rem: These LEDs are connected to port A *
* 68332 TPU lines: from TPU0 to TPU7 (CHA0 to CHA7) *
* Leds switch on following the cycle *
* D8 -> D7 -> .... -> D1 then -> D8 -> D7 ... etc *
* Leds switch on by applying a 0 PA0=0 -> PA1=0 .... etc *
* Led lighting time duration is about 1S *
* This time is generated by "program" loop *
*
* FILE NAME: CHEN1_1_PA.SRC *
*****
* Inclusion of file specifying the different labels
include EID210.def
section code
*****
* MAIN PROGRAM *
*****
* INITIALISE
*****
* Configure port A into "Discrete Input Output" mode -> code $8
START move.w #$8888,CFSR3 * CHA0 to CHA3 into "Discrete Input Output" mode
move.w #$8888,CFSR2 * CHA4 to CHA7 into "Discrete Input Output" mode
move.w #$FFFF,CPR1 * All bits in first 16 bits of port A are set to 1
*
* MAIN LOOP
*****
Deb_BP move.w #$5556,HSRR1 * Only D8 lights up
jsr ATT
move.w #$5559,HSRR1 * Only D7 lights up
jsr ATT
move.w #$5565,HSRR1 * Only D6 lights up
jsr ATT
move.w #$5595,HSRR1 * Only D5 lights up
jsr ATT
move.w #$5655,HSRR1 * Only D4 lights up
jsr ATT
move.w #$5955,HSRR1 * Only D3 lights up
jsr ATT
move.w #$6555,HSRR1 * Only D2 lights up
jsr ATT
move.w #$9555,HSRR1 * Only D1 lights up
jsr ATT
bra Deb_BP
*
* END of main program
*****

*****
* SUB-PROGRAMS *
*****

* Waiting sub-program of about 1 second
*****
ATT move.l #$001FFFFFF,d2
ATT1 sub.l #1,d2
bne ATT1
rts * Return from sub-program
END of sub-program
*****

end
* END of Assembler source file
*****

```

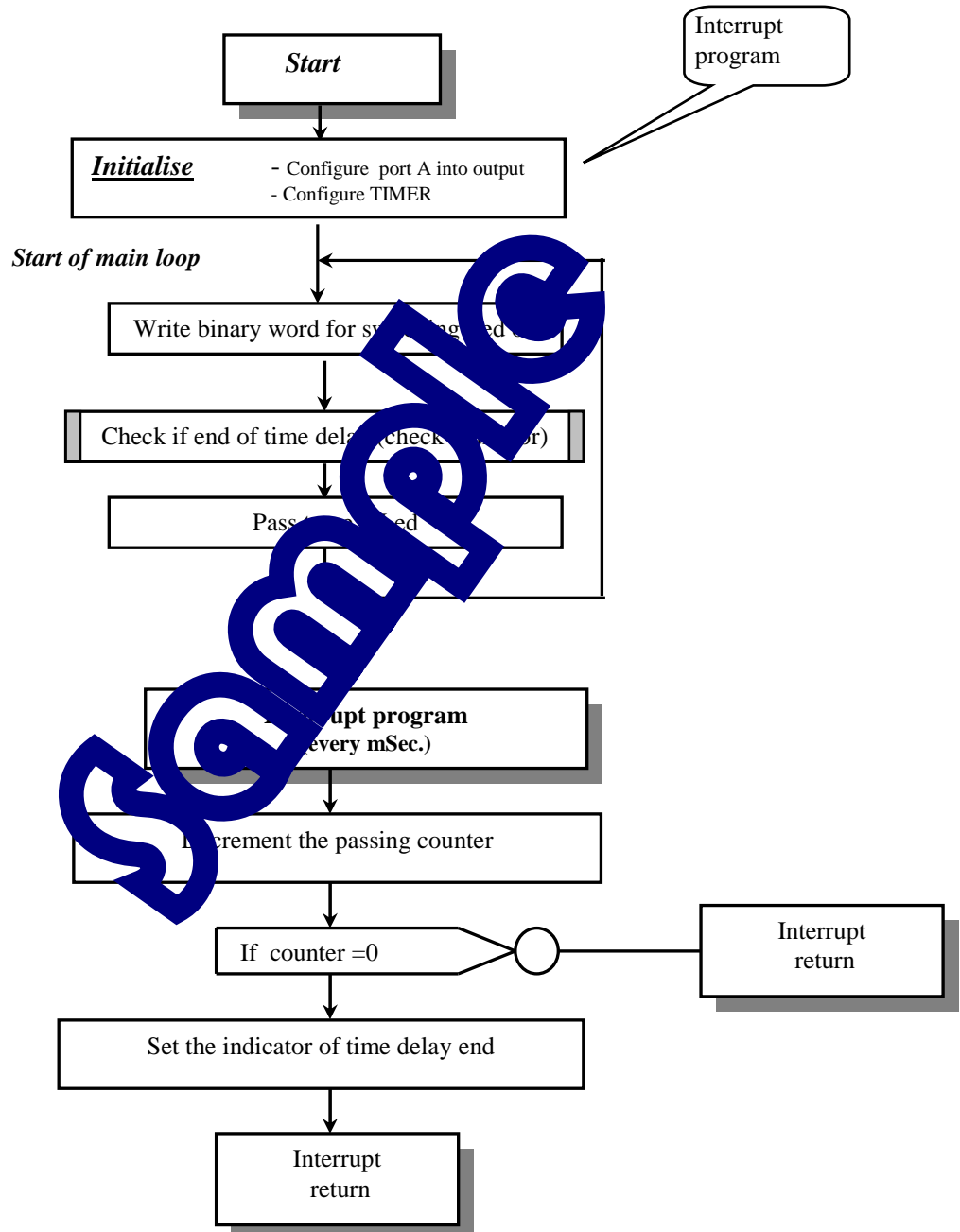
### 1.2.4 Flowchart, solution with time delay carried out by micro-controller "Timer" function

For having periodic interruption every 1 mS, both registers which labels have been specified in file EID210.def, must be initialised :

"PICR" (Periodic Interrupt Control Register) to \$0760

"PITR" (Periodic Interrupt Timer Register) to \$0008.

On the other hand, the vector table must be initialised and interrupt program must be allowed.



## 1.2.5 Program in A68xxx Assembler, solution with time delay carried out by micro-controller "Timer" function

```

*****
* EXPERIMENTS ON EID210 BOARD WITH INPUT/OUTPUT SIMULATOR *
* Carrying out of light shift device on Leds of port A *
*****
* Specification : *
*****
* Rem: Lines of port A are connected to lines of 68332 TPU: *
* TPU0 to TPU7 (CHA0 to CHA7) *
* TPU lines of 68332: TPU0 to TPU7 (CHA0 to CHA7) *
* Leds switch on by applying a 0 *
* PA0=0 -> PA1=0 .... etc *
* Led lighting time duration is about 1S *
* This time is generated by the 68332 Timer *
* FILE NAME: CHENI_2_PA.SRC (solution N°2) *
*****
* Inclusion of the file specifying the different labels *
include EID210.def

*****
* Declaration of variables *
*****
        section      var
COUNTER ds.l        1
INDICATOR ds.b      1

*****
* Start of execute program *
*****
        section      code
* INITIALISE
*****
* Configure port A into "Discrete Input Output" mode -> configure $
START  move.w        #$8888,CFSR3      * Configure CHA3 in "DIO" mode
        move.w        #$8888,CFSR2      * Configure CHA4 to CHA7 in "DIO" mode
        move.w        #$FFFF,CPR1      * Configure 16 bits in first priority
        move.w        #$0003,CTRL_0     *

* Configure the time base
        move.l        #96,CCR1          * 96 is the interrupt vector n°
        move.l        #it_bt,CCR1      * f_it-bt is the interrupt function address
        asl.l         #2,d0             *
        add.l         #tab_vectors,d0  * Initialise the vectors table
        move.l        d0,a0
        move.l        a1,(a0)
        move.l        #1000,COMPTEUR   * 1000*1mS = 1S
        move.b        #$00,INDICATEUR  * end of counting
        move.w        #$0008,PITR      * 1 interrupt every 1 ms
        move.w        #$0760,PICR

*
* MAIN LOOP
*****
Deb_BP move.w        #$5556,HSRR1      * Only D8 lights up
ATT1  move.b        INDICATEUR,D2      * Waiting for end of time delay
        cmp.b        #01,D2
        bne         ATT1
        move.l        #1000,COMPTEUR   * 1000*1mS = 1S
        move.b        #$00,INDICATEUR  * end of counting

ATT2  move.w        #$5559,HSRR1      * Only D7 lights up
        move.b        INDICATEUR,D2      * Waiting for end of time delay
        cmp.b        #01,D2
        bne         ATT2
        move.l        #1000,COMPTEUR   * 1000*1mS = 1S
        move.b        #$00,INDICATEUR  * end of counting
        move.w        #$5565,HSRR1      * Only D6 lights up

```

```

ATT3   move.b    INDICATEUR,D2      * Waiting for end of time delay
        cmp.b    #01,D2
        bne     ATT3
        move.l   #1000,COMPTEUR    * 1000*1mS = 1S
        move.b   #00,INDICATEUR    * end of counting

ATT4   move.w    #$5595,HSRR1      * Only D5 lights up
        move.b   INDICATEUR,D2    * Waiting for end of time delay
        cmp.b   #01,D2
        bne     ATT4
        move.l   #1000,COMPTEUR    * 1000*1mS = 1S
        move.b   #00,INDICATEUR    * end of counting

ATT5   move.w    #$5655,HSRR1      * Only D4 lights up
        move.b   INDICATEUR,D2    * Waiting for end of time delay
        cmp.b   #01,D2
        bne     ATT5
        move.l   #1000,COMPTEUR    * 1000*1mS = 1S
        move.b   #00,INDICATEUR    * end of counting

ATT6   move.w    #$5955,HSRR1      * Only D3 lights up
        move.b   INDICATEUR,D2    * Waiting for end of time delay
        cmp.b   #01,D2
        bne     ATT6
        move.l   #1000,COMPTEUR    * 1000*1mS = 1S
        move.b   #00,INDICATEUR    * end of counting

ATT7   move.w    #$6555,HSRR1      * Only D2 lights up
        move.b   INDICATEUR,D2    * Waiting for end of time delay
        cmp.b   #01,D2
        bne     ATT7
        move.l   #1000,COMPTEUR    * 1000*1mS = 1S
        move.b   #00,INDICATEUR    * end of counting

ATT8   move.w    #$9555,HSRR1      * Only D1 lights up
        move.b   INDICATEUR,D2    * Waiting for end of time delay
        cmp.b   #01,D2
        bne     ATT8
        move.l   #1000,COMPTEUR    * 1000*1mS = 1S
        move.b   #00,INDICATEUR    * end of counting

        bra     Deb_B              * END of main loop
*      END of main program
*****

*****
*      INTERRUPT FUNCTION          *
*      linked to time base        *
*****
it_bt  sub.l     #$00000001,COMPTEUR
        cmp.l    #00000000,COMPTEUR
        bne     it_ret             * Return if not equal to 0
        move.b   #01,INDICATEUR    * End of time delay
        move.l   #1000,COMPTEUR    * Reset of time delay
it_ret  rte                          * Interrupt return
End of interrupt program
*****

        end
* End of source file

```

**Sample**

# EXPERIMENT N° 2 – DUPLICATION OF ONE 8 BITS INPUT PORT ONTO 8 BITS OUTPUT PORT.

## 2.1 Topic

<b><i>Purpose :</i></b>	<b>Additional abilities:</b>  Being capable of configuring one inputs / outputs port onto input port. Being capable of acquiring the state of these inputs (acquisition technique specific to the 68332 micro-controller TPU).
<b><i>Specifications :</i></b>	The states of the 8 "SW" CHIP connected to port B of the EID210 Board is duplicated to the 8 LEDs connected to port A.

### Necessary Equipment :

PC Micro-Computer using Windows 97 or latter,  
 68332 Micro-Controller 8 Bits Input / Output Board, Ref. : EID 100 000  
 USB link cable, or if you have a parallel cable, Ref. : EGD 000 003  
 AC/AC 8V Power Supply 1 A, Ref. : EGD000001,  
 Input / Output Simulator, Ref. : EID0001000

Duration : 4 hours

## 1.3 Elements of solution

### 1.3.1 Acquisition of "Switches" states

Configure the bits of port B into input:

As shown on the Simulator Board layout given in ANNEX, "switches" of the inputs / outputs simulator are connected onto port B of the EID210 Board.

As shown on the EID210 Board layout, bits of port B belong to the 68332 Micro-controller TPU outputs, with the following correspondence:

N° bit TPU	15	14	13	12	11	10	9	8
N° bit Port B	7	6	5	4	3	2	1	0

The operating mode of a micro-controller TPU line is determined in loading a 4 bits code into a register dedicated to this purpose (Registers CFSR<sub>i</sub> with i=0,1,2,3 on 16 bits, as specified in file to be included "EID210.def"), following the next correspondence:

Bit of CFSR0	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TPU link (N° CHANNEL)	15				14				13				12			
Bit Port B	7												4			
Bit of CFSR1	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TPU link (N° CHANNEL)	11				10				9				8			
Bit Port B	3								1				0			

In this case, the requested operating mode is a simple Outputs mode.

In the 68332 Micro-controller Technical Data Handbook, and more particularly in Chapter dedicated to the "TPU", this simple Inputs/Outputs mode is called "DIO" (Discrete Input Output).

In this case, the 4 bits binary code to be loaded in configuration registers must be: 1000 = \$8

Let instructions enabling configuration of port B into mode "DIO":

move.w	#8888	CFSR0
move.w	#8888	CFSR1

Acquisition technique of the input

When the input state acquisition is required, logical binomial "11" must be written to corresponding locations of HSSR0 service register.

"SWITCH" N°	1	2	3	4	5	6	7	8								
Bit N° into port B	7	6	5	4	3	2	1	0								
TPU "CHANNEL" N°	15	14	13	12	11	10	9	8								
Bits of register HSSR0	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

When all 8 "SWITCHES" states acquisition is required, then all register HSSR0 must be loaded with binomials "11", let value be \$FFFF.

When writing binary binomial "11", there is input state memorisation into 16 bits memory (called state memory) carrying out a FIFO type cell (First In First Out). The last stored state is the bit of rank 15. For knowing the input state at the moment of the last writing of binomial "11" into register HSSR0, it is sufficient to check this bit of rank 15.

The state memory address of rank i "CHANNEL" is inferred from the definition given in file EID210.def (file to be included), due to operation CH\_state + CTRL\_TPi



### 1.3.2 Activation of outputs

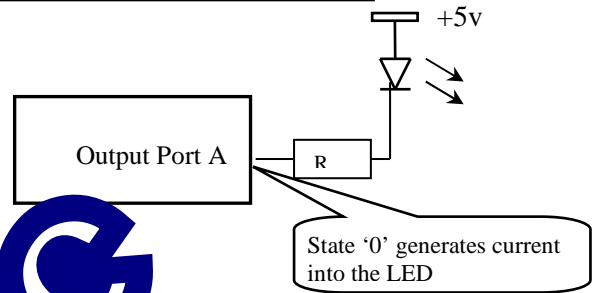
LEDs are connected to port A of EID210 processor Board.

Port A is connected to outputs CH0 (TPU0) <-> PA0 to CH7 (TPU7) <-> PA7 of the micro-controller.

For setting one bit of port A to logic state '1', a binary binomial "0 1" must be set into the corresponding location of register HSRR1 (which address is specified into the definition file EID210.def). For setting to logic state '0' value "1 0" must be set to the same binomial.

Led N°	D1	D2	D3	D4	D5	D6	D7	D8
Bit N° into port A	7	6	5	4	3	2	1	0
Bits of register HSRR1	15 14	13 12	11 10	9 8	7 6	5 4	3 2	1 0

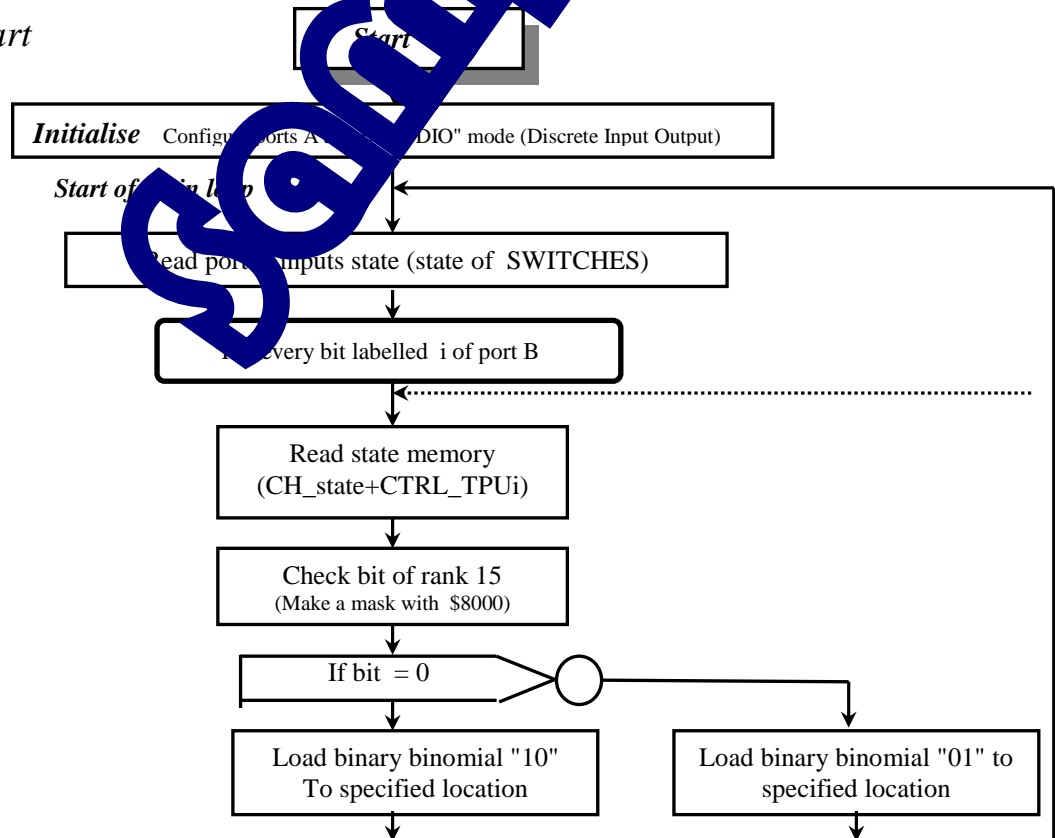
For switching a Led on, a logic state '0' must be written into the bit of the corresponding port (As indicated on next digit)



**Example :** If we want Led D8 switching on, and the output LEDs, register HSRR1 must be loaded by the value :

N° of the concerned diode	:	D0	D1	D2	D3	D4	D5	D6	D7	D8	
Value Output port :		1	1	1	1	1	1	1	1	0	
Value into register HSRR1 :		01	01	01	01	01	01	01	01	10	= \$5556

#### Flowchart



### 1.3.3 Program in A68xxx Assembler

```

*****
*      EXPERIMENT ON EID210 WITH INPUTS/OUTPUTS SIMULATOR      *
*      Duplicate the "Switches" state ( port B) onto Leds ( port A) *
*****
* Specifications *
*****
* State of "SWITCHES" is duplicated onto LEDs *
* Remark: These LEDs are connected to port A *
* -> TPU lines of 68332: TPU0 to TPU7 (CHA0 to CHA7) *
* "SWITCHES" are connected to port B *
* -> TPU lines of 68332: TPU0 to TPU7 (CHA8 to CHA15) *
* *
* *
* FILE NAME: RECOP_BsA.SRC *
*****
* Inclusion of the file specifying the different labels *
include EID210.def
* Definition of constants *
*****
CH_etat equ 2
*****
* Start of the execute program *
*****
section code
* INITIALISE
*****
* Configure port A in "Discrete Input Output" (DIO) mode -> code $8
START move.w #8888,CFSR3 * CHA0 to CHA7 in "DIO" mode
      move.w #8888,CFSR2 * CHA8 to CHA15 in "DIO" mode
      move.w #8888,CFSR1 * CHA0 to CHA7 in "DIO" mode
      move.w #8888,CFSR0 * CHA8 to CHA15 in "DIO" mode
* Specify priorities
      move.w #FFFF,CPR1 * All bits of PA in priority
      move.w #FFFF,CPR0 * All bits of PA in priority
* The input states are stored into state registers
*When 11 will be written into service register
      move.w #AAAA,HSQR0 * All bits of PA will be stored
* All leds switched off
      move.w #5555,HSRR1 * All bits PA to 1
      move.w #5555,HSRR0 * All bits PA to 0 -> image of HSRR1
*
* MAIN LOOP
*****
Deb_BP * Acquire inputs
      move.w #FFFF,HSRR1
* Check state of PB7 then, position PA7
      move.w CH_etat+CTRL_TPU8,d4 * Read state register of PB7
      btst #15,d4
      beq b7_0
      bclr #15,d0 * If 1, prepare for having PA7=1
      bset #14,d0
      bra b7_1
b7_0 bset #15,d0 * If 0, prepare for having PA7=0
      bclr #14,d0
b7_1 move d0,HSRR1 * Load onto port A
* Check state of PB6 then, position PA6
      move.w CH_etat+CTRL_TPU9,d4 * Read state register of PB6
      btst #15,d4
      beq b6_0
      bclr #13,d0 * If 1, prepare for having PA6=1
      bset #12,d0
      bra b6_1
b6_0 bset #13,d0 * If 0, prepare for having PA6=0
      bclr #12,d0
b6_1 move d0,HSRR1 * Load onto port A
* Continued next page

```

```

* Check state of PB5 ,then position PA5
move.w      CH_etat+CTRL_TPU10,d4
btst       #15,d4
beq        b5_0
bclr      #11,d0
bset      #10,d0
bra       b5_1
b5_0      bset      #11,d0
          bclr      #10,d0
b5_1      move      d0,HSRR1

* Check state of PB4 ,then position PA4
move.w      CH_etat+CTRL_TPU11,d4
btst       #15,d4
beq        b4_0
bclr      #9,d0
bset      #8,d0
bra       b4_1
b4_0      bset      #9,d0
          bclr      #8,d0
b4_1      move      d0,HSRR1

* Check state of PB3, then position PA3
move.w      CH_etat+CTRL_TPU12,d4
btst       #15,d4
beq        b3_0
bclr      #7,d0
bset      #6,d0
bra       b3_1
b3_0      bset      #7,d0
          bclr      #6,d0
b3_1      move      d0,HSRR1

Check state of PB2, then position PA2
move.w      CH_etat+CTRL_TPU13,d4
btst       #15,d4
beq        b2_0
bclr      #5,d0
bset      #4,d0
bra       b2_1
b2_0      bset      #5,d0
          bclr      #4,d0
b2_1      *move     d0,HSRR1

* Check state of PB1, then position PA1
move.w      CH_etat+CTRL_TPU14,d4
btst       #15,d4
beq        b1_0
bclr      #3,d0
bset      #2,d0
bra       b1_1
b1_0      bset      #3,d0
          bclr      #2,d0
b1_1      move      d0,HSRR1

* Check state of PB0, then position PA0
move.w      CH_etat+CTRL_TPU15,d4
btst       #15,d4
beq        b0_0
bclr      #1,d0
bset      #0,d0
bra       b0_1
b0_0      bset      #1,d0
          bclr      #0,d0
b0_1      move      d0,HSRR1

bra        Deb_BP

* End of main loop -> loop
End of main program
*****
End of file
*****
end

```

**Sample**

# EXPERIMENT N° 2- CONTROL OF 7 SEGMENTS DISPLAY

## 1.4 Topic

<p><b>Purpose :</b></p>	<p><b>Additional Abilities:</b></p> <p>Being capable of displaying a digital data in using a '7 segments' display device.</p> <p>Being capable of transcoding a 'Binary Decimal Code' (BCD) information into a control information of a 7 segments display.</p> <p>Being capable of programming a computer science structure 'SELECT IN'-type.</p>
	<p><b>Variant n°1: Decimal display</b></p> <p>On the 7 segments display device, we should like to see digits from 0 to 9 displayed with a recurrence of about one second per digit.</p> <p><b>Variant n°2: Hexadecimal display</b></p> <p>On the 7 segments display device, we should like to see the 15 hexadecimal characters (0 to 9 then A, B, C, D, E and F) displayed with a recurrence of one second per digit.</p>

### Necessary Equipment :

PC Micro-Computer using Windows ® 95 or latter,  
 68332 Micro-Controller 16/32 bits Mother Board, Ref. : EID 100 000  
 USB link cable, or if unavailable RS232 cable, Ref. : EGD 000 003  
 AC/AC 8V Power Supply, 1 A, Ref. : EGD000001,  
 Input / Output Simulator, Ref. : EID001000

Duration : 4 hours

## 1.5 Elements of solution

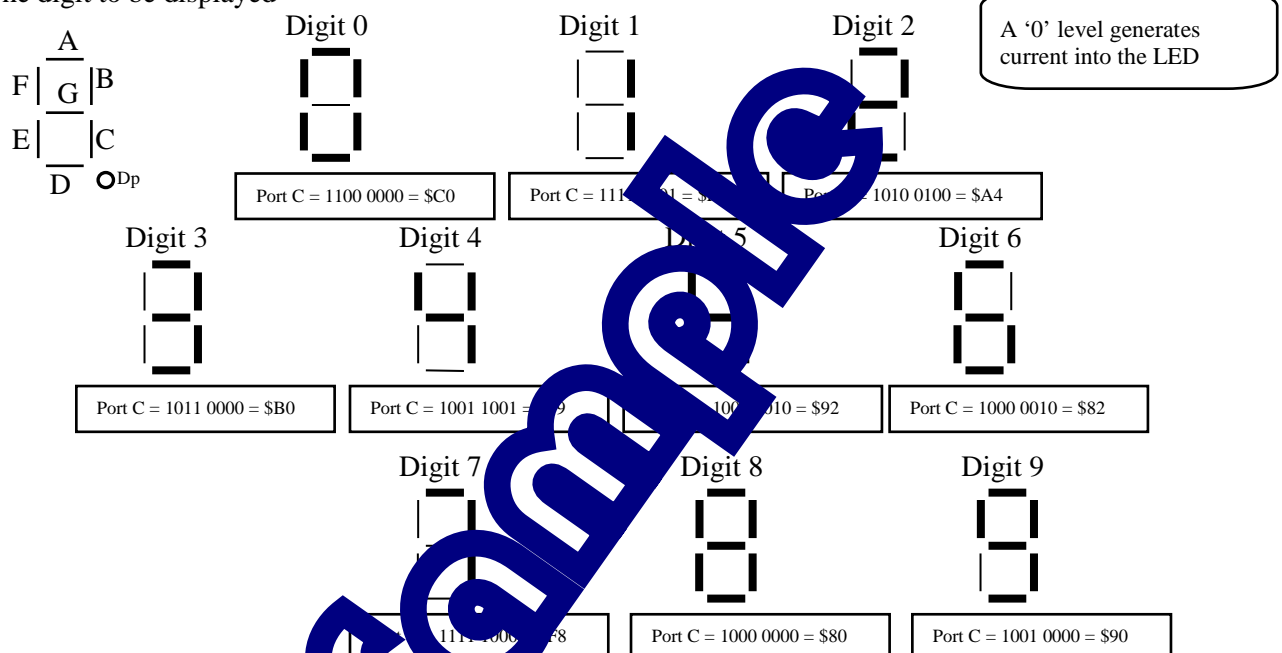
### 1.5.1 Outputs activation

As shown on layout given in ANNEX, we see that the 7 segments display is connected to port C of the processor board, with the following correspondence :

Bits Port C :	7	6	5	4	3	2	1	0
Segment :	Dp	G	F	E	D	C	B	A

On the other hand, the display device is « COMMON ANODE » - type, which means that a logic 0 must be written onto an output for switching on the corresponding « LED ».

Determination of the logic states of port C, function of the digit to be displayed



#### Initialisation and writing:

Before using a bit of port C in output, the associated direction register must be initialised (label DIR\_Port\_C, which address is specified in definition file EID210.def that must be included).

A logic level '1' must be written to the corresponding place into the direction register for enabling the use of a bit of port C as an output.

In this case, we must write \$FF00 (location onto MSB).

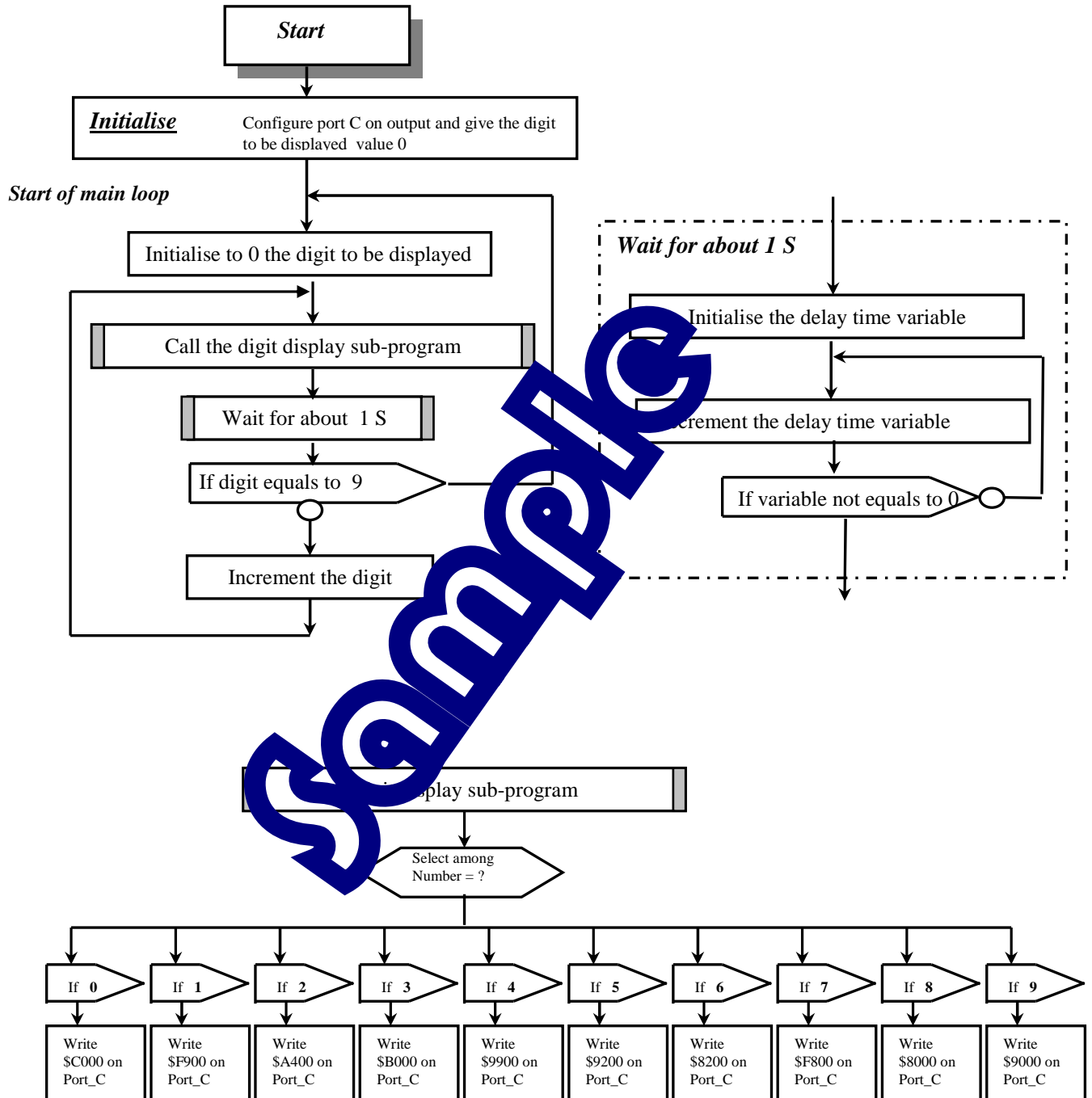
For activating the output bits, the value must be written into the data register associated to port C (label Port\_C, which address is specified in definition file EID210.def).

Example :

If we require the display of digit '8' then, instruction must be written  
Because the value must be placed onto the word MSBs.

```
Move.w #8000,Port_C
```

### 1.5.2 Decimal display Flowcharts (Variant n°1)



### 1.5.3 Decimal display program in A68xxx Assembler (Variant n°1)

```

*****
* EXPERIMENTS ON EID210 BOARD WITH INPUTS/OUTPUTS SIMULATOR *
*****
*
*      Check of port C controlling the 7 segments display device
*      for the display of a decimal digit ( 0 to 9)
*
* Description:
*****
* The display device displays a decimal digit (between 0 and 9)
* incrementing itself every second
* This time duration is generated by a "program" loop
*
* FILE NAME: T_Port_C_1.SRC
*****
*****

*****
*      Declaration of variables
*****
      section      var
NOMBRE ds.b      1      * 8 bits size
* Inclusion
*****
* Inclusion of the file specifying the different labels
      include      EID210.def

*****
* Start of execute program
*****
      section      code

*      INITIALISE
*****
Start      move.w   #$FF00,DIR_Port_C * Port C is configured in output mode
                                         level 0 sets output operation

*      MAIN LOOP
*****
*Increment digit
Deb_BP     move.b   NOMBRE,d0      Register "do" is an image of NOMBRE
           cmp.b   #9,d0
           bne    Etiq1
           move.b  #0,d0
           bra    Etiq2
Etiq1     add.b   #1,d0
Etiq2     move.b   d0,NOMBRE
* Go to display the result
           jsr    AFFICHER
* Waiting loop of about 1 second
           move.l  #$01FFFFFF,d2
ATT       sub.l   #1,d2
           bne    ATT
* Pass to the next digit
           bra    Deb_BP
*End of main loop
*****
*****
* End of main program
*****

* Continued next page...

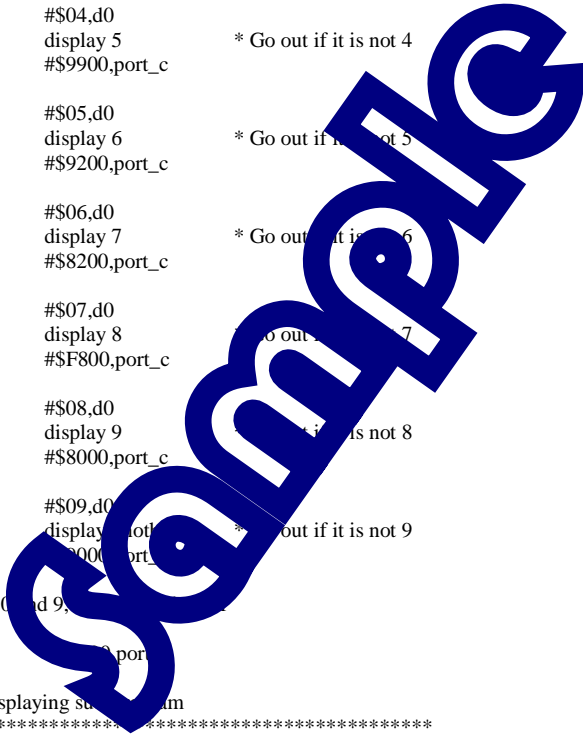
```



```

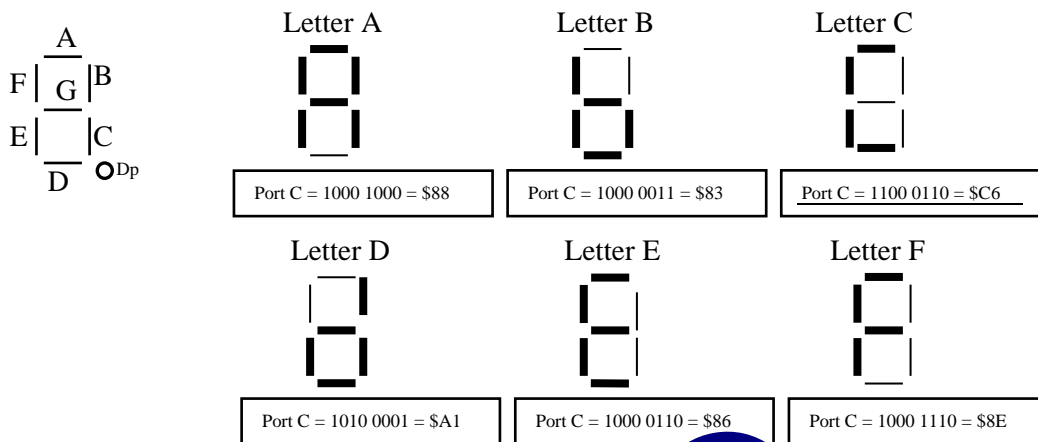
*****
* Transcoding sub-program *
* "Decimal Coded Binary" -> 7 Segments *
* and display *
*****
DISPLAY
    cmp.b        #$00,d0
    bne          display 1      * Go out if it is not 0
    move.w      #C000,Port_c
    rts
display1  cmp.b        #$01,d0
    bne          display2      * Go out if it is not 1
    move.w      #F900,Port_c
    rts
display2  cmp.b        #$02,d0
    bne          display 3      * Go out if it is not 2
    move.w      #A400,Port_c
    rts
display3  cmp.b        #$03,d0
    bne          display 4      * Go out if it is not 3
    move.w      #B000,Port_c
    rts
display4  cmp.b        #$04,d0
    bne          display 5      * Go out if it is not 4
    move.w      #9900,port_c
    rts
display5  cmp.b        #$05,d0
    bne          display 6      * Go out if it is not 5
    move.w      #9200,port_c
    rts
display6  cmp.b        #$06,d0
    bne          display 7      * Go out if it is not 6
    move.w      #8200,port_c
    rts
display7  cmp.b        #$07,d0
    bne          display 8      * Go out if it is not 7
    move.w      #F800,port_c
    rts
display8  cmp.b        #$08,d0
    bne          display 9      * Go out if it is not 8
    move.w      #8000,port_c
    rts
display9  cmp.b        #$09,d0
    bne          display_nothing * Go out if it is not 9
    move.w      #0000,port_c
    rts
*If the digit is not between 0 and 9
display_nothing
    move.w      #0000,port_c
    rts
* End of transcoding and displaying sub-program
*****

* End of listing
*****
end
  
```

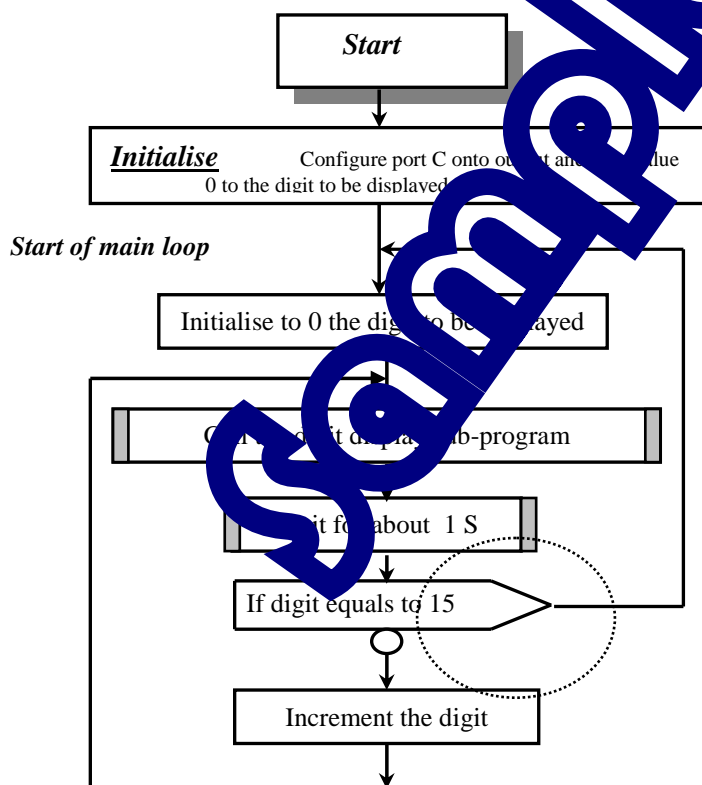


### 1.5.4 Modifications to be made for complying with Variant n°2

Complement for representing letters A, B C, D, E and F



Modification on the Flowchart:



### 1.5.5 Program in A68xxx Assembler of hexadecimal display (Variant n°2)

```

*****
* EXPERIMENTS ON EID210 BOARD WITH INPUTS/OUTPUTS SIMULATOR *
*****
*          Test of port C, controlling the 7 segments display device          *
*          for displaying an hexadecimal value (from 0 to 15)                *
*                                                                              *
* Description:                                                                *
*****
* The display device displays an hexadecimal digit (between 0 and 15)      *
* let be: 0,1,2,3,4,5,6,7,8,9,A,b,C,d E,F                                  *
* incrementing itself every second                                          *
* This time duration is generated by a "program" loop                       *
*                                                                              *
* FILE NAME: T_Port_C_2.SRC                                                 *
*****

*****
* Declaration of variables *
*****
      section      var
NOMBRE ds.b      1          * 8 bits size

* Inclusion
*****
* Inclusion of the file specifying the different labels
include          EID210.def

*****
* Start of execute program *
*****
      section      code

* INITIALISE
*****
* Port C
start      move.w  #FFF0,DIR_Port_C * Port C configuration: output
                                         level 1 sets output operation

* Digit to display
      clr          NOMBRE
      clr          d0          * Register "d0" is an image of NOMBRE

* MAIN LOOP
*****
Deb_BP * Start of main loop
* Go to display the current digit
      jsr         AFFICH_DIGIT
* Waiting loop of about 1 second
      move.l      #1,d0
ATT      sub.l     #1,d0
      bne        ATT

* Increment digit
      cmp.b       #15,d0
      bne        Etiq1        * If it is not equal to 15, increment
      clr.b      d0          * If it is equal to 15, start again from 0
      bra        Etiq2

Etiq1    add.b    #1,d0
Etiq2    move.b   d0,NOMBRE

* Pass to the next digit
      bra        Deb_BP

* End of main loop
*****
* End of main program *
*****

```

```

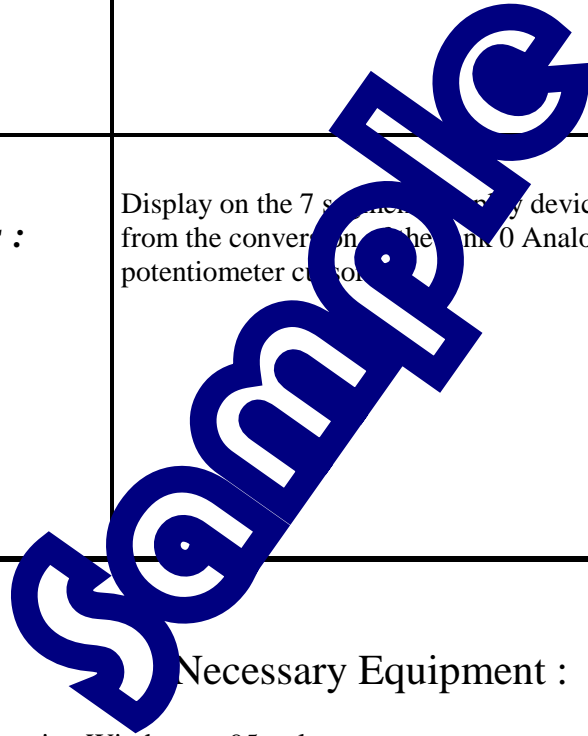
*****
*      Transcoding sub-program      " Hexadecimal" -> 7 Segments & display *
*****
AFFICHER      cmp.b      #$00,d0
               bne      display1      * Go out if it is not 0
               move.w   #$C000,Port_c
               rts
display1      cmp.b      #$01,d0
               bne      display2      * Go out if it is not 1
               move.w   #$F900,Port_c
               rts
display2      cmp.b      #$02,d0
               bne      display3      * Go out if it is not 2
               move.w   #$A400,Port_c
               rts
display3      cmp.b      #$03,d0
               bne      display4      * Go out if it is not 3
               move.w   #$B000,Port_c
               rts
display4      cmp.b      #$04,d0
               bne      display5      * Go out if it is not 4
               move.w   #$9900,port_c
               rts
display5      cmp.b      #$05,d0
               bne      display6      * Go out if it is not 5
               move.w   #$9200,port_c
               rts
display6      cmp.b      #$06,d0
               bne      display7      * Go out if it is not 6
               move.w   #$8200,port_c
               rts
display7      cmp.b      #$07,d0
               bne      display8      * Go out if it is not 7
               move.w   #$F800,port_c
               rts
display8      cmp.b      #$08,d0
               bne      display9      * Go out if it is not 8
               move.w   #$8000,port_c
               rts
display9      cmp.b      #$09,d0
               bne      display10     * Go out if it is not 9
               move.w   #$9000,port_c
               rts
display10     cmp.b      #$0A,d0
               bne      display11     * Go out if it is not 10 ($A)
               move.w   #$8800,port_c
               rts
display11     cmp.b      #$0B,d0
               bne      display12     * Go out if it is not 11 ($B)
               move.w   #$9000,port_c
               rts
display12     cmp.b      #$0C,d0
               bne      display13     * Go out if it is not 12 ($C)
               move.w   #$C600,port_c
               rts
display13     cmp.b      #$0D,d0
               bne      display14     * Go out if it is not 13 ($D)
               move.w   #$A100,port_c
               rts
display14     cmp.b      #$0E,d0
               bne      display15     * Go out if it is not 14 ($E)
               move.w   #$8600,port_c
               rts
display15     cmp.b      #$0F,d0
               bne      display_nothing * Go out if it is not 15 ($F)
               move.w   #$8E00,port_c
               rts
display1_nothing move.w   #$FF00,port_c * If it is out from $00 to $0F, switch display device off.
               rts
* End of transcoding and display sub-program
*****
* End of listing
*****
end

```

## TP 2 DISPLAY OF POTENTIOMETER POSITION

### 2.1 Topic

<p><i>Purpose :</i></p>	<p><b>Complementary abilities:</b></p> <p>Being capable of configuring one Analogue -&gt; Digital Converter.</p> <p>Being capable of detecting the end of one Analogue -&gt; Digital Converter.</p>
<p><i>Cahier des charges :</i></p>	<p>Display on the 7 segment display device the 4 most significant bits resulting from the conversion of the analog 0 Analogue input, on which is connected the potentiometer cursor.</p>



**Necessary Equipment :**

- PC Micro-Computer using Windows ® 95 or latter,
- 68332 Micro-Controller 16/32 bits Mother Board, Ref. : EID 100 000
- USB link cable, or if unavailable RS232 cable, Ref. : EGD 000 003
- AC/AC 8V Power Supply, 1 A, Ref. : EGD000001,
- Input / Output Simulator, Ref.. : EID001000

Duration : 2 hours

## 2.2 Elements of solution

Conversion of Analogue input:

The used Analogue -> Digital Converter is a MAX196. It can convert up to 6 Analogue inputs. The input to be converted is the rank '0' channel.

A conversion demand is carried out by writing a control word, which format is the following:

7	6	5	4	3	2	1	0
PD1	PD0	ACQ	RNG	BIP	A2	A1	A0

Bits A2, A1 and A0 specify the Analogue input rank to be converted.

RNG	BIP	Range
0	0	0 to 5V
0	1	0 10V
1	0	+5V
1	1	+10V

A2	A1	A0	Ana. input rank
0	0	0	0
0	0	1	1
0	1	0	2
0	1	1	3
1	0	0	4
1	0	1	5

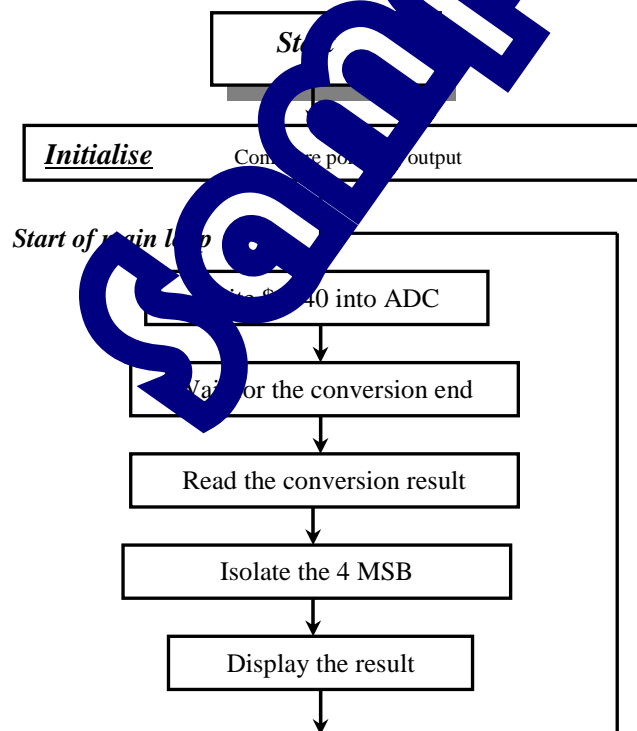
Both bits RNG and BIP specify the selected Analogue input variation range.

Bits PD1,PD0, ACQ must be initialised to 010.

Word 0100 0000 = \$0040 must be written to the ADC address (in file EID210.def, file to be included).

Conversion is not immediate. The end of conversion can be known by reading the rank 14 bit of the state system.

### 2.2.1 Flowchart



## 2.2.2 Program in Assembler A68xxx

```

*****
*           EXPERIMENTS ON EID210 BOARD WITH INPUTS/OUTPUTS SIMULATOR           *
*****
*           Display on 7 segments device of n°0 Analogue input conversion result     *
*           (the potentiometer's one)                                             *
*                                                                                   *
* Specifications:                                                                 *
*****
* One hexadecimal digit (between 0 and 15) is displayed, corresponding to the MSB of the E0 Analogue input *
* conversion result (set by the potentiometer position)                          *
* FILE NAME: T_CAN_Port_C.SRC                                                    *
*****

* Inclusion
*****
* Inclusion of the file specifying the different labels
include          EID210.def

*****
* Start of the execute program
*****
section          code

* INITIALISE
*****
* Port C
Start            move.w          #$FF00,DIR_Port_C          * Port C is configured in output
                                                         * Level 1 sets output operation

* MAIN LOOP
*****
Deb_BP * Start of main loop
* Start the Analogue -> Digital conversion of channel 0
move.w          #$0040,AN0                                *
* Wait for the end of conversion (test of the "A->end of conversion" of the state register)
Att_F_C move.w          REG_ETAT,D0
and.w          #0x00000000,REG_ETAT,D0
bne            Att_F_C

* Read the conversion result
move.w          C0,C0
and.w          #$0000000F,C0

* Keep only the 4 MSB
lsl.w          #4,C0

* Go to display the result
jsr            AFFICHER

• Loop -> Start again
• bra          Deb_BP

* End of main loop
*****
* End of main program
*****

*****
* Transcoding sub-program
* " Hexadecimal" -> 7 Segments
* & display
*****
DISPLAY        cmp.b          #$00,d0
               bne            display1
               move.w         #$C000,Port_c
               rts
               * Go out if it is not 0

```

```

display1      cmp.b      #$01,d0
              bne      display2      * Go out if it is not 1
              move.w   #$F900,Port_c
              rts
display2      cmp.b      #$02,d0
              bne      display3      * Go out if it is not 2
              move.w   #$A400,Port_c
              rts
display3 cmp.b  #$03,d0
              bne      display4      * Go out if it is not 3
              move.w   #$B000,Port_c
              rts
display4 cmp.b  #$04,d0
              bne      display5      * Go out if it is not 4
              move.w   #$9900,port_c
              rts
display5      cmp.b      #$05,d0
              bne      display6      * Go out if it is not 5
              move.w   #$9200,port_c
              rts
display6      cmp.b      #$06,d0
              bne      display7      * Go out if it is not 6
              move.w   #$8200,port_c
              rts
display7      cmp.b      #$07,d0
              bne      display8      * Go out if it is not 7
              move.w   #$F800,port_c
              rts
display8      cmp.b      #$08,d0
              bne      display9      * Go out if it is not 8
              move.w   $8000,port_c
              rts
display9      cmp.b      #$09,d0
              bne      display10     * Go out if it is not 9
              move.w   #$9000,port_c
              rts
display10     cmp.b      #$0A,d0
              bne      display11     * Go out if it is not 10 ($A)
              move.w   #$8800,port_c
              rts
display11     cmp.b      #$0B,d0
              bne      display12     * Go out if it is not 11 ($B)
              move.w   #$8300,port_c
              rts
display12     cmp.b      #$0C,d0
              bne      display13     * Go out if it is not 12 ($C)
              move.w   ?
              rts
display13     cmp.b      #$0D,d0
              bne      display14     * Go out if it is not 13 ($D)
              move.w   #$7000,port_c
              rts
display14     cmp.b      #$0E,d0
              bne      display15     * Go out if it is not 14 ($E)
              move.w   #$8600,port_c
              rts
display15     cmp.b      #$0F,d0
              bne      display_nothing * Go out if it is not 15 ($F)
              move.w   #$8E00,port_c
              rts
* If it is out from $00 to $0F, switch display device off.
display_nothing move.w   #$FF00,port_c
              rts
* End of transcoding and display sub-program
*****
* End of listing
*****
end

```

